

6. (Amended) A soil compaction device according to claim 1, wherein the positioning unit has a fluid-activated piston/cylinder unit as well as an electromechanical valve controlled by the signal from the sensor unit to control a fluid stream at the piston/cylinder unit.
7. (Amended) A soil compaction device according to claim 1, wherein two operator elements are provided that move independent of one another and through which the phase relationship of a group of rotating eccentric masses can be changed.
8. (Amended) A soil compaction device according to claim 1, wherein the operator element can be tilted away from a spring effect from a zero position, and in this zero position its overall force resulting from the rotating eccentric masses has no horizontal component.
9. (Amended) A soil compaction device according to claim 1, wherein, in addition to the operator element, a remote control unit is provided with a sending unit that can be spatially separated from the soil compaction device and with a receiving unit attached to the soil compaction device, wherein a signal can be produced by the receiver unit to control the positioning unit.

ABSTRACT OF THE DISCLOSURE:

Please add page 9 as the Abstract of the Disclosure.

REMARKS

This application has been amended to insert headings in the specification, to eliminate multiple dependencies in the claims and otherwise placing the claims into better conformance with preferred USPTO practice without narrowing the claims, and to add an Abstract of the Disclosure. Entry of the amendments and early consideration and allowance are respectfully requested.